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Overview

- Depth First Search
- Topical sorting

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Objective

- Understand and be able to apply the depth first search (DFS) algorithm
- Apply Topological Sorting as graph algorithm

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Knights Tour Problem

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- Puzzle played on chess board with single figure, the knight
- Objective: find sequence of moves that allow knight to visit every square on board "exactly" once
- Such sequence is called "tour"
- Upper bound on possible tours is 1.35 * 10³⁵
- Use graph search to solve problem

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Knights Tour Problem

Solve problem by using two main steps:

- Represent legal moves of knight on chessboard as graph
- Use a graph algorithm to find path of length rows×columns-1 where every vertex on graph is visited exactly once

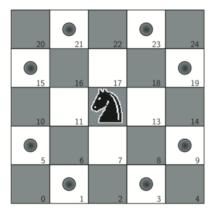
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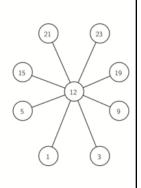
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Knights Tour Problem

- Each square represented as node in graph
- Each legal move represented by edge





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Building the Graph

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```
from Graph import Graph

def knightGraph(bdSize):
    ktGraph = Graph()
    for row in range(bdSize):
        for col in range(bdSize):
            nodeId = posToNodeId(row,col,bdSize)
            newPositions = genLegalMoves(row,col,bdSize)
            for e in newPositions:
                  nid = posToNodeId(e[0],e[1],bdSize)
                  ktGraph.addEdge(nodeId,nid)
    return ktGraph

def posToNodeId(row, column, board_size):
    return (row * board_size) + column
```

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Building the Graph

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Complete Graph

- 336 edges
- Less connections for vertices on edges of board
- Sparsity:

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- Fully connected graph: 4096 egdes
- Matrix only 8.2% filled

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Depth First Search (DFS)

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- Solve problem width depth first search (DFS) algorithm
- Creates search tree by exploring one branch of the tree as deeply as possible
- We will look at two algorithms:
 - Directly solves problem by explicitly forbidding a node to be visited more than once
 - 2. More general, but allows nodes to be visited more than once as the tree is constructed

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Implementing Knight's Tour

- DFS exploration of graph finds path with exactly 63 edges
- When dead end is found (more moves possible)
 - Algorithm backs up tree to next deepest vertex allowing a legal move

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knighTour - Function

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```
from Graph import Graph, Vertex

def knightTour(n,path,u,limit):
    u.setColor('gray')
    path.append(u)
    if n < limit:
        nbrList = list(u.getConnections())
        i = 0
        done = False
        while i < len(nbrList) and not done:
            if nbrList[i].getColor() == 'white':
                  done = knightTour(n+1, path, nbrList[i], limit)
        i = i + 1
        if not done: # prepare to backtrack
        path.pop()
        u.setColor('white')
    else:
        done = True
    return done</pre>
```

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DFS - Coloring

- DFS uses colors to keep track which vertices have been visited
 - White: unvisited
 - Gray: visited
- If neighbors of particular vertex have been explored && length of vertices < 64 => dead end reached
- If dead end reached => backtrack (Return from knightTour wirh false)

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DFS - Coloring

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- Since DFS is recursive, use stack to help with backtracking
- After return from knightTour with status False:
 - Remain inside while loop
 - Look at nextvertex in nbrlist

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Simple Example

- Following figures show steps of search
- Assume getConnections orders nodes in alphabetical order
- Start with calling knightTour(0,path,A,6)

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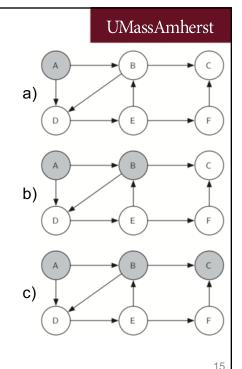
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Simple Example

- knightTour starts with node A (a))
- B and D are adjacent to A
- Since B comes next in alphabet, it is chosen next (b))
- Recursively calling knightTour explores B



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Simple Example

- B is adjacent to C and D
- knightTour elects to explore C
- C is dead end with no adjacent white notes (c))
- Change color of C back to white (d))
- Backtracks search to vertex B

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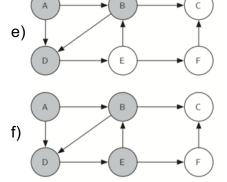
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Simple Example



g) B C F

- Next vertex to explore is D (e))
- knightTour makes recursive calls until we get to node C again (f), g), h))

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Simple Example

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- when we get to node C the test n < limit fails
- => all nodes in graph exhausted
- return True to indicate that we have made a successful tour of the graph
- return the list, path has the values [A,B,D,E,F,C], which is the the order we need to traverse the graph to visit each node exactly once

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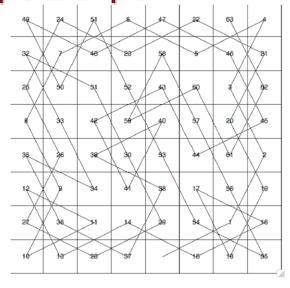
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Simple Example

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Complete tour around8 x 8 board

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Knight's Tour - Analysis

- Very sensitive to method used to select next vertex
- Example
 - 5 x 5 board, calculate path in 1.5 second
 - 8 x 8 board, up to ½ hour
- Reason: $O(k^N)$, N is number of squares, k is small constant

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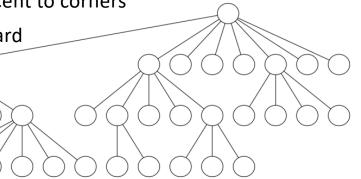
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Knight's Tour - Analysis

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- Root is starting point of search tree
- Then checks each move knight can make
 - 2 legal moves in corner
 - 3 in squares adjacent to corners
 - 8 in middle of board



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Knight's Tour - Analysis

- Figure shows number of possible moves on board
- Next level of tree has again 2 8 next possible moves
- Number of possible positions to examine corresponds to number of nodes in search tree

2	3	4	4	4	4	3	2
3	4	6	6	6	6	4	3
4	6	8	8	8	8	6	4
4	6	8	8	8	8	6	4
4	6	8	8	8	8	6	4
4	6	8	8	8	8	6	4
3	4	6	6	6	6	4	3
2	3	4	4	4	4	3	2

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Knight's Tour - Analysis

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- Number of nodes in binary tree is $2^{N+1}-1$
- Number much larger for tree with up to 8 nodes
- Use average branch factor to estimate number of child nodes: k^{N+1} -1, k is average branching factor
- Example:
 - 5 x 5 board, tree is 25 levels deep => N=24
 - $k=3.8 \Rightarrow 3.8^{25}-1 = 3.12 * 10^{14}$

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Knight's Tour - Analysis

- Way to speed up 8 x 8 case => runs in less than 1 second
- orderbyAvail will be called used instead of u_getConnections (shown in previous code)
- Line 10 is critical one, it ensures to select vertex that has *fewest* available moves
- But why not select node that has most available moves?

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Knight's Tour - Analysis

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Knight's Tour - Analysis

- Problem with using vertex with most available moves => tends to have knight visit middles squares early on
 - Easy for night to get stranded on one side of board and cannot reach other side.
- Visiting squares with fewest available moves first pushes knight to visit squares around edges
- Using intuition is called heuristic!

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General Depth First Search

- Implementation extends graph class by adding:
 - Time instance variable and methods dfs and dfsvisit
 - dfs method iterates over all vertices in graph calling dfsvisit on white nodes
 - This ensures all nodes in graph are considered and no vertices are left out of depth first forest

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General Depth First Search

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General Depth First Search

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- DFS method starts with single vertex startVertex and explores all neighboring white vertices as deeply as possible
- dfsvisit is almost identical to bfsexcept
- dfsvisit uses a stack where bfsexcept uses queue
 - Not visible in code but implicit of dfsvisit

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General Depth First Search

- Following sequence of figures illustrates DFS in action
- Dotted lines indicate checked edges but node on other end of edge has already been added to DFS tree
- In the code this is realized by checking that color of the other node is non-white

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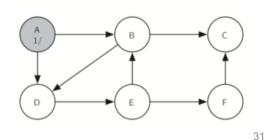
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General Depth First Search

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- Search begins at vertex A
- Since all vertices are white algorithm visits vertex A
 - 1. Set color of vertex A gray => vertex is being explored
 - 2. Discovery time is set to 1
 - Neighbors B and D need to be visited as well
 - Arbitrary decision to visit adjacent nodes in alphabetic order



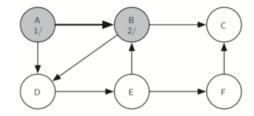
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General Depth First Search

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- Vertex B is visited next
 - 1. Its color is set to gray
 - 2. Discovery time is set to 2
 - 3. B is adjacent to C and D
 - 4. Visit vertex C next



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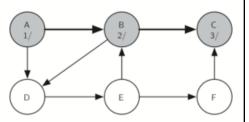
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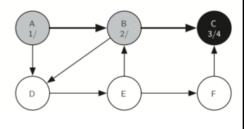
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General Depth First Search

- Visiting C brings alg. to end of branch of tree
 - Color node gray and set discovery time to 3
 - 2. No adjacent vertices to C
 - 3. Color vertex black, set finish time to 4



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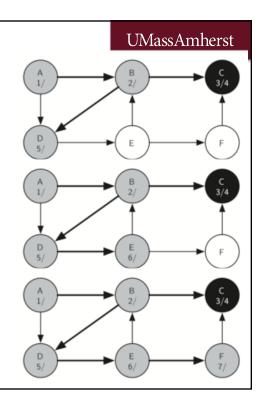
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General Depth First Search

- Now return to B and explore nodes adjacent to it
- Only addition vertex is D
 - Visit D and continue search
 - Results in exploring E, which has adjacent vertices B and F
 - B is already colored, thus explore F



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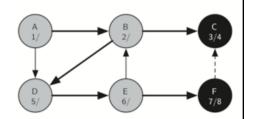
General Depth First Search

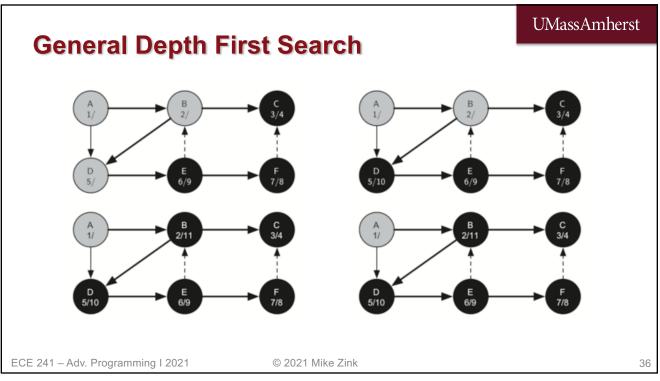
- F has only adjacent vertex C
 - C already colored black
 - Nothing else to explore
 - Reached end of branch
- Algorithm works its way back to first node
 - setting finish times and
 - coloring vertices black

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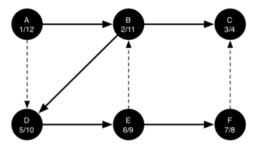
General Depth First Search

- Start and finishing times are called parentheses property
- All children of particular node in DFS
 - Have later discovery time than parent
 - Have earlier finish time than parent
- Figure shows final tree constructed by DFS algorithm



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General Depth First Search

- General running time:
 - Loops in dfs run in O(V), since executed once for each vertex in graph
 - Since dfsvisit only called recursively if vertex is white, loop will execute max. once for every edge in graph => O(E)
- Total time for DFS is O(V+E)

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Topological Sorting

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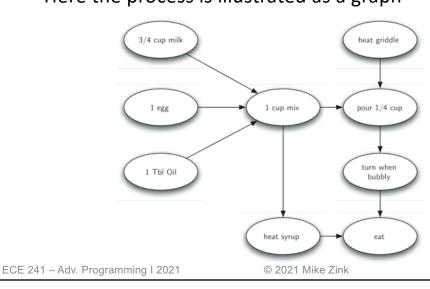
- Demonstrate that almost anything can be turned into a graph problem
- Consider problem of stirring up batch of pancakes
- Recipe: 1egg, 1 cup of pancake mix, 1 tablespoon oil and ¾ cup of milk
- Heat griddle, mix all ingredients together, and spoon mix onto hot griddle
- When pancakes start bubbling, turn them over
- Heat up syrup

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Topological Sorting

Here the process is illustrated as a graph



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Topological Sorting

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- · Problem: Know what to do first
- Start by heating griddle or adding any of ingredients to pancake mix
- To make that decision we turn to algorithm called topological sort

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Topological Sorting

- Topological sort takes DAG and produces linear ordering of all vertices such that
 - If graph contains edge (v, w) then vertex v comes before vertex w.
- Other examples besides pancakes:
 - project schedules
 - Multiplying matrices

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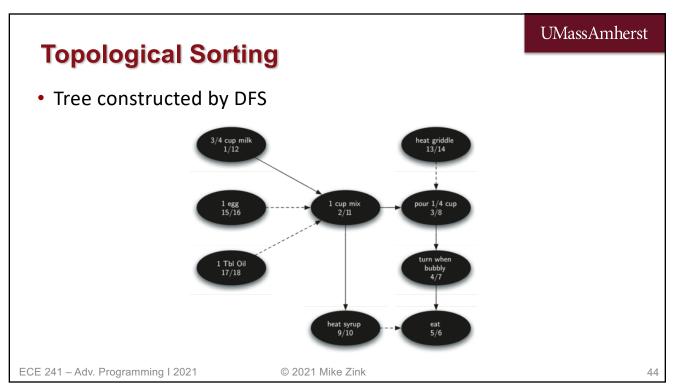
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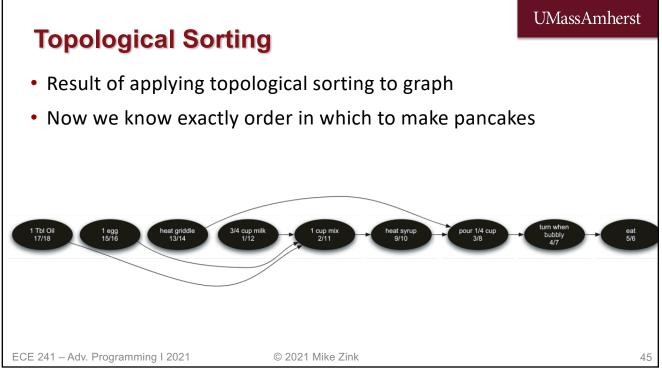
Topological Sorting

- Algorithm for Topological Sort (adaptation of DFS):
 - 1. Call dfs (g) for some graph g. Main reason, call finish times for each vertex
 - 2. Store vertices in a list in decreasing order of finish time
 - Return the ordered list as the result of the topological sort

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Next Steps

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• Next lecture on Tuesday: State Machines

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